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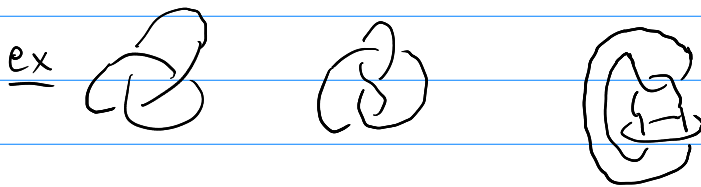
The Jones Polynomial

* Requisite knot theory

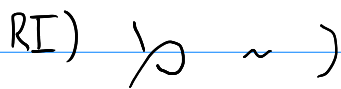
def A link L is a smooth/PL 1-dim'd closed submfld of S^3 , up to (ambient) isotopy of S^3 — a smooth map $f: [0,1] \times S^3 \rightarrow S^3$ such that $f_t: S^3 \rightarrow S^3$ is a diffeomorphism for each t , with $f_0 = \text{id}$ and $f_1(L) = L'$.

A knot is a 1-component link.

def A knot/link diagram D is a 4-regular graph embedded in S^2 whose vertices are marked like X , representing a generic projection of a link.



Reidemeister moves:

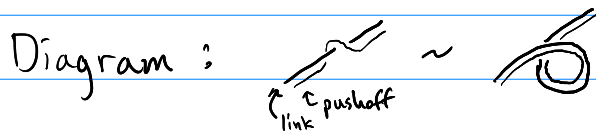


knots/links up to isotopy \longleftrightarrow diagrams up to RI, RII, RIII

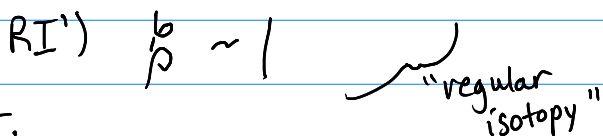
def A framed knot/link is a link along with a trivialization of its normal bundle, up to a suitable notion of isotopy

Only need a section, and represent as embedding of $L \times [0,1]$, with $L \times \{0\}$ the link and $L \times \{1\}$ the pushoff.

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framed knots/links up to isotopy \leftrightarrow diagrams up to RII, RIII, and



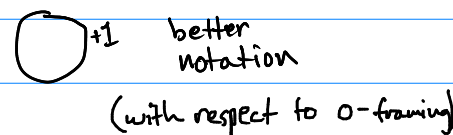
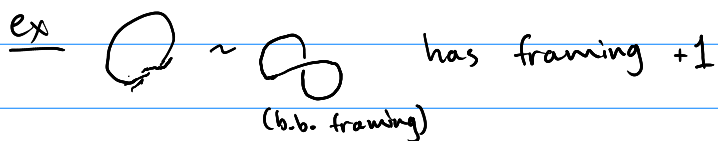
Framing is a $\mathbb{Z}^{\# \text{components}}$ -torsor.

Thm There is a distinguished 0-framing of every component of an oriented link.

Pf Let Σ be a Seifert surface of L ($\partial \Sigma = L$, with induced orientation).

This is Poincaré dual to $\alpha \in H^1(S^3 - L)$ such that $\alpha(\mu) = 1$

with $\mu \rightarrow \bigcirc^L$, for all such μ . Take a regular neighborhood of L in Σ \square



def Let D be an oriented diagram, and L the corresponding framed oriented link, from the blackboard framing.

The writhe $w(D) = \sum$ framings of $L \in \mathbb{Z}$.

thm $\mapsto +1$ $\mapsto -1$ to compute $w(D)$

ex $w(\bigcirc^3) = 3$

thm For knots, writhe is invariant under ori. reversal.

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* Kauffman bracket (Kauffman 1987)

$$\langle \text{diagram} \rangle \in \mathbb{Z}[A^{\pm 1}], \quad A = t^{-1/4}$$

(i) $\langle \bigcirc \rangle = \delta := -A^2 - A^{-2}$ (traditionally 1)

(ii) $\langle D_1 \sqcup D_2 \rangle = \langle D_1 \rangle \langle D_2 \rangle$

(iii) $\langle \text{crossing} \rangle = A \langle \text{A-state} \rangle + A^{-1} \langle \text{B-state} \rangle$

each diagram differs only inside

so $\langle \text{diagram} \rangle = \sum_{\text{states}} A^{\#(\text{A-states}) - \#(\text{B-states})} \delta^{\#(\text{loops})}$ (2ⁿ terms state sum)

ex $\langle \text{loop} \rangle = A \langle \text{loop} \rangle + A^{-1} \langle \bigcirc \rangle$
 $= (A + A^{-1}(-A^2 - A^{-2})) \langle \bigcirc \rangle = -A^{-3} \langle \bigcirc \rangle$

sim. $\langle \text{loop} \rangle = -A^3 \langle \bigcirc \rangle$ Can use $\begin{matrix} \diagdown & \leftrightarrow & \diagup \\ A & \leftrightarrow & A^{-1} \end{matrix}$

ex $\langle \text{twist} \rangle = A \langle \text{twist} \rangle + A^{-1} \langle \text{twist} \rangle$
 $= A \langle \text{twist} \rangle + A^{-1} \langle \text{twist} \rangle = (-A^4 - A^{-4}) \delta$
 $= (-A^5 - A^{-3} + A^{-7}) \delta$

def The Jones polynomial of an oriented link L with an oriented diagram D is

$$V_L(t) = \underbrace{(-A^{-3})^{w(D)}}_{\text{same as adding twists to zero-out framings}} \langle D \rangle \delta^{-1} \quad \text{with } A = t^{-1/4}$$

(L ≠ ∅ for this normalization)

(4)

$$\begin{aligned} \text{ex } V(\mathcal{P}) (t) &= (-A^{-3})^3 (-A^5 - A^{-3} + A^{-7}) \\ &= t + t^3 - t^4 \end{aligned}$$

• $V_L(t) \in \mathbb{Z}[t^{\pm 1/2}]$, and for knots $\in \mathbb{Z}[t^{\pm 1}]$

• $V(L_1 \# L_2) = \delta^{-1} V(L_1) V(L_2)$

• $V(\underbrace{(K_1) \text{---} (K_2)}_{\text{connect sum}}) = V(K_1) V(K_2)$

• $V_L(t) = V_L(t^{-1})$

↑ mirror image. $X \leftrightarrow X$ in diagrams

ex $\mathcal{B} \approx \mathcal{B}$ (known to Dehn 1914)

• $\deg V_L(t) \leq \text{crossing number} = \min_{D \neq L} \# \text{crossings} \dots$ used to resolve a Tait conj. ...