

July 28

Superposition "to place over" aka. linearity

Recall: If A is a matrix and $A\vec{x}_1 = \vec{b}_1$ and $A\vec{x}_2 = \vec{b}_2$, then $A(c_1\vec{x}_1 + c_2\vec{x}_2) = c_1\vec{b}_1 + c_2\vec{b}_2$. $\vec{b}_2 = \vec{0}$ is the special case of adding a homogeneous solution to a particular. So: to get a solution to a linear comb. of \vec{b}_1 and \vec{b}_2 , linearly combine \vec{x}_1 and \vec{x}_2 in the same way. More generally, this is just if $AX = B$, then $A(X\vec{c}) = B\vec{c}$.

Linear diff. eqs, too, have this property.

ex $y'' + 3y' + 2y = e^{4t} + e^{-t}$

i) solve $y'' + 3y' + 2y = e^{4t}$ } ii.5) $y'' + 3y' + 2y = 0$
 $r = -1, -2$ $r = 4$
 $y = Ae^{-t} + Be^{-2t}$

guess $y_p = Ae^{4t}$
 $y_p' = 4Ae^{4t}$
 $y_p'' = 16Ae^{4t}$

$16Ae^{4t} + 12Ae^{4t} + 2Ae^{4t} = e^{4t}$
 $30Ae^{4t} = e^{4t} \Rightarrow A = \frac{1}{30}$

ii) solve $y'' + 3y' + 2y = e^{-t}$
 $r = -1$

guess $y_p = Ate^{-t}$
 $y_p' = -Ate^{-t} + Ae^{-t}$
 $y_p'' = Ate^{-t} - 2Ae^{-t}$

$(Ate^{-t} - 2Ae^{-t}) + 3(-Ate^{-t} + Ae^{-t}) + 2(Ate^{-t}) = e^{-t}$
 $-2A \qquad \qquad \qquad +3A \qquad \qquad \qquad = 1$

$\Rightarrow A = 1$

iii) solve $y'' + 3y' + 2y = e^{4t} + e^{-t}$
 $y = \frac{1}{30}e^{4t} + te^{-t} + Ae^{-t} + Be^{-2t}$

Thm (Existence and uniqueness). if $y'' + ay' + by = f(t)$ is a diff. eq. with a solution y_p , and if t_0, y_0, y_1 are constants, then there is a unique solution y with $y(t_0) = y_0$ and $y'(t_0) = y_1$.

Pf there is a unique solution y_q to $y'' + ay' + by = 0$ with $\begin{bmatrix} y_q(t_0) \\ y_q'(t_0) \end{bmatrix} = \begin{bmatrix} y_0 \\ y_1 \end{bmatrix} - \begin{bmatrix} y_p(t_0) \\ y_p'(t_0) \end{bmatrix}$.

By superposition, $y = y_q + y_p$ is a solution to $y'' + ay' + by = f$, and $y_0 = y_q(t_0) + y_p(t_0)$ and $y_1 = y_q'(t_0) + y_p'(t_0)$.

Conversely, the difference between any two solutions is a homogeneous solution with init. conditions $\begin{bmatrix} 0 \\ 0 \end{bmatrix}$, so the difference is the 0 function. \square

This means that even with a "driving term" solutions for a particular initial condition is unique. If no particular solution exists, the equation has no solutions. (but this basically never happens).

ex $y'' + y = \cos(\omega t)$
 $r = \pm i$ $r = \pm \omega i$

Two cases:

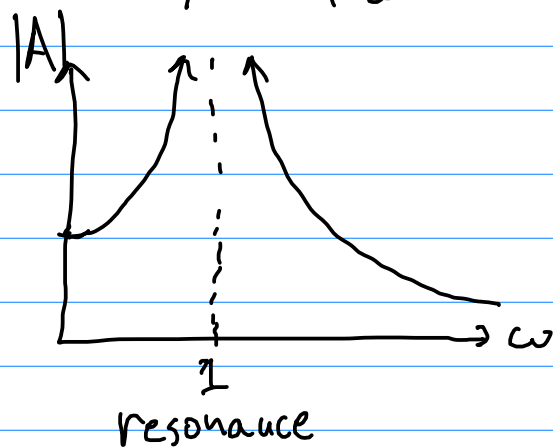
1) $|\omega| \neq 1$. Then $y_p = A \cos \omega t + B \sin \omega t$
 $y_p' = -A \omega \sin \omega t + B \omega \cos \omega t$
 $y_p'' = -A \omega^2 \cos \omega t - B \omega^2 \sin \omega t$

$$\text{so } \begin{cases} -A\omega^2 + A = 1 \\ -B\omega^2 + B = 0 \end{cases}$$

$$A = \frac{1}{1-\omega^2} \quad B = 0$$

$$y_p = \frac{1}{1-\omega^2} \cos(\omega t)$$

$$\text{general: } y = \frac{1}{1-\omega^2} \cos(\omega t) + C \cos t + D \sin t$$



$$(2) |\omega|=1$$

$$y_p = At \cos t + Bt \sin t$$

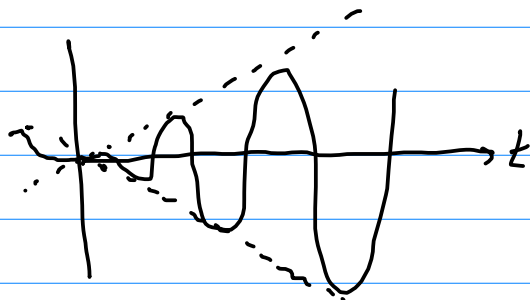
$$y_p' = -At \sin t + A \cos t + Bt \cos t + B \sin t$$

$$y_p'' = -At \cos t - 2A \sin t - Bt \sin t + 2B \cos t$$

$$\cos t: \quad 2B = 1 \quad B = \frac{1}{2}$$

$$\sin t: \quad -2A = 0 \quad A = 0$$

$$\text{solution: } y = \frac{1}{2} t \cos t + C \cos t + D \sin t$$



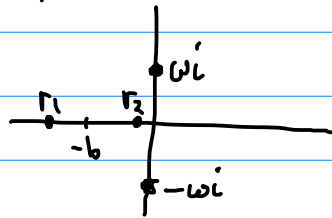
Larger and
larger amplitudes
at resonance!

ex Let's add dampening: $y'' + 2by' + y = \cos \omega t$

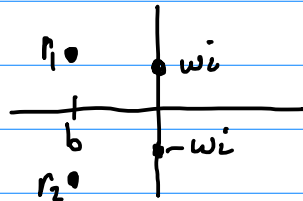
$$r = \frac{-2b \pm \sqrt{4b^2 - 4}}{2} = -b \pm \sqrt{b^2 - 1} \quad \pm \omega i$$

Now there is no way for $-b \pm \sqrt{b^2 - 1} = \pm \omega i$

For $b^2 \geq 1$,



For $b^2 < 1$,



$$y_p = A \cos \omega t + B \sin \omega t$$

$$y_p' = -A \omega \sin \omega t + B \omega \cos \omega t$$

$$y_p'' = -A \omega^2 \cos \omega t - B \omega^2 \sin \omega t$$

$$\begin{aligned} \cos: & (-A\omega^2) + 2b(B\omega) + A = 1 & \begin{cases} (1-\omega^2)A + 2b\omega B = 1 \\ -2b\omega A + (1-\omega^2)B = 0 \end{cases} \\ \sin: & (-B\omega^2) + 2b(-A\omega) + B = 0 \end{aligned}$$

$$\begin{bmatrix} A \\ B \end{bmatrix} = \begin{bmatrix} 1-\omega^2 & 2b\omega \\ -2b\omega & 1-\omega^2 \end{bmatrix}^{-1} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \frac{1}{(1-\omega^2)^2 + 4b^2\omega^2} \begin{bmatrix} 1-\omega^2 \\ 2b\omega \end{bmatrix}$$

$$y_p = \frac{1}{(1-\omega^2)^2 + 4b^2\omega^2} \left((1-\omega^2) \cos \omega t + 2b\omega \sin \omega t \right)$$

Notice: as $b \rightarrow 0$, we get prev. solution

Fact: $A \cos \omega t + B \sin \omega t = \underbrace{\sqrt{A^2 + B^2}}_{\text{amplitude}} \cos(\omega t - k)$ for some k .

The amplitude of the above is

$$\frac{1}{\sqrt{(1-\omega^2)^2 + 4b^2\omega^2}}$$

peak is when $\frac{d}{d\omega}((1-\omega^2)^2 + 4b^2\omega^2) = 0$

$$\parallel$$
$$2(1-\omega^2)(-2\omega) + 8b^2\omega = 0$$

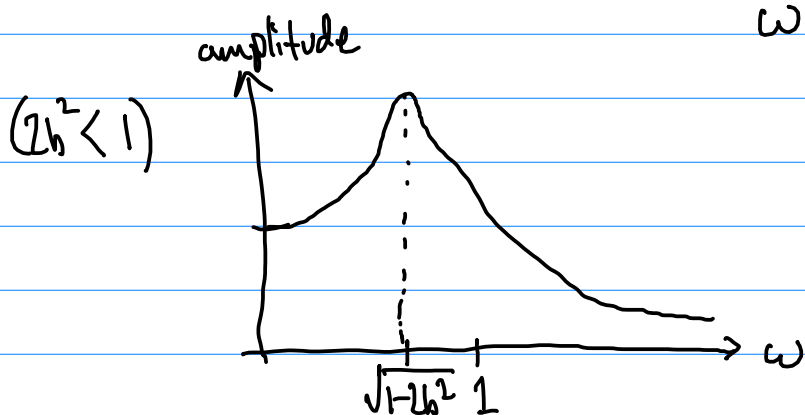
one critical point at $\omega=0$ (ignore)

$$\text{now } 2(1-\omega^2)(-2) + 8b^2 = 0$$

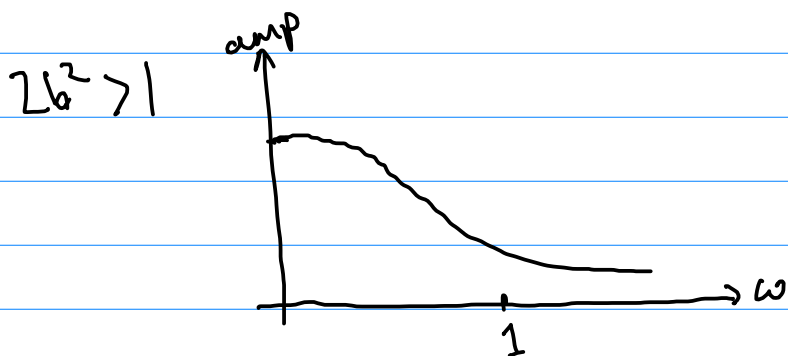
$$-4 + 4\omega^2 + 8b^2 = 0$$

$$\omega^2 = 1 - 2b^2$$

$$\omega = \pm \sqrt{1 - 2b^2}$$



as $b \rightarrow 0$, peak $\rightarrow 1$
and becomes
an asymptote.



no peak at all!
too much dampening
for driver to
do anything at
any frequency!

Variation of parameters

If $y'' + ay' + by = 0$ has y_1, y_2 lin. indep solutions,
then $y'' + ay' + by = f$ has particular solution

$$y_p = v_1(t) y_1(t) + v_2(t) y_2(t)$$

$$\text{with } v_1(t) = \int \frac{-f(t) y_2(t) dt}{y_1(t) y_2'(t) - y_1'(t) y_2(t)}$$

$$\text{and } v_2(t) = \int \frac{f(t) y_1(t) dt}{y_1(t) y_2'(t) - y_1'(t) y_2(t)}$$

$$\left(\text{that is, } v_1 = \int \frac{-f y_2 dt}{W[y_1, y_2]} \text{ and } v_2 = \int \frac{-f y_1 dt}{W[y_1, y_2]} \right)$$

The book gives the derivation, but there is no need to do it over and over. Read it, though.

ex $y'' - y = \tan t$

$$e^{-t}, e^t \quad r = \pm 1 \quad v_1 = \int \frac{-\tan(t) e^t dt}{W[e^{-t}, e^t]} \quad v_2 = \int \frac{\tan(t) e^{-t} dt}{W[e^{-t}, e^t]}$$