Discussion 21: Modeling With Differential Equations (9.1)

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- 1. Verify that the following differential equations have the given solutions, where y is a function of t.
 - (a) For y' = ay, the solutions $y = Ce^{at}$ for $C \in \mathbb{R}$.

(b) For y'' + y = 0, the solutions $y = C \sin(t)$ and $y = C \cos(t)$ for $C \in \mathbb{R}$.

(c) For ty' = 1, the solutions $y = \ln(t) + C$ for $C \in \mathbb{R}$.

- 2. Determine the general solution to the given differential equation.¹
 - (a) y' = 0.

(b) $y'(t) = \sin(t)$

¹(Hint: this is integration by another name.)

(c)
$$y'(t) = t^2$$

(d)
$$y''(t) = -\frac{1}{t^2}$$

3. Find the equilibrium solutions 2 to the following differential equations.

(a)
$$\frac{dy}{dt} = ay$$
 for $a \neq 0$. (What happens if $a = 0$?)

(b)
$$\frac{dy}{dt} = 1 - y^2$$
.

(c)
$$\frac{dy}{dt} = 1 + y^2$$
.

(d)
$$\frac{dy}{dt} = ay(b-y)$$
 for $a \neq 0$.

(e)
$$\frac{dy}{dt} = \cos(y)$$
.

²An equilibrium solution is a constant-valued solution y(t) = c for some $c \in \mathbb{R}$.

4. An object of mass m hanging from an ideal spring with spring constant k obeys the second-order differential equation

$$\frac{d^2x}{dt^2} = -\frac{k}{m}x,$$

where x(t) is the vertical displacement through time.

(a) Show that $x(t) = A\cos(t\sqrt{k/m}) + B\sin(t\sqrt{k/m})$ is a solution, where $A, B \in \mathbb{R}$.

(b) Solve the initial value problem where x(0) = 1 and x'(0) = 0, representing releasing the object from one unit of displacement at rest.

(c) Solve the initial value problem where x(0) = 0 and x'(0) = 1, representing giving the object a unit-sized kick at time zero.

5. Suppose g(t) is a function. Write the solution y(t) for y'(t) = g(t) using a definite integral, given the initial condition y(0) = C.

6. Guess the general solution y(t) for $y^{(n)} = 0$. (Hint: What kinds of functions become zero after repeated differentiation?)

7. Suppose y = f(t) and y = g(t) are two solutions to y'' + ay' + by = 0. Show that y = Af(t) + Bg(t) is also a solution, for all constants $A, B \in \mathbb{R}$.

8. An equilibrium solution y(t) = c for a first-order differential equation y'(t) = g(y) is called *stable* if there is an interval (a, b) containing c such that g(y) is positive for $y \in (a, c)$ and g(y) is negative for $y \in (c, b)$. Analyze the stability of equilibrium solutions in problem 3. Can you make intuitive sense of this terminology?